

Quantitative Social Science Methods, I, Lecture

Notes: Missing Data

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August 17, 2020

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 - **Robust:** separate missingness and analysis models

Readings

j.mp/MisMeas

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- Gary King; James Honaker; Anne Joseph O'Connell; Kenneth Scheve. “[Analyzing Incomplete Political Science Data: An Alternative Algorithm for Multiple Imputation](#)” APSR, 2001.

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- Amelia II: A Program for Missing Data

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- Quiz: If some values don't exist, what analysis would you do?

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 - Adding variables to predict income can change NI to MAR

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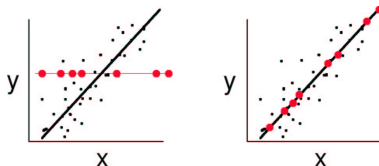
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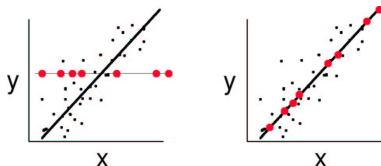
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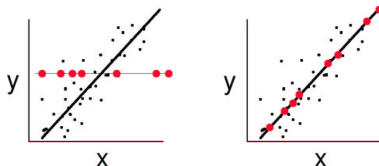
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- $\hat{y}$ Regression Imputation: Optimistic (scatter when observed, perfectly linear when unobserved?); SEs too small
- $\hat{y} + \epsilon$ Regression Imputation: Ignores estimation uncertainty; impossible with scattered missingness; getting there

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- **Little known about M :** Specifying $P(M|D_{obs}, \gamma)$ hard

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- **Little known about M :** Specifying $P(M|D_{obs}, \gamma)$ hard
- **NI models:** (Heckman, many others) often don't do well when can be evaluated

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Multiple Imputation

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- **Run whatever statistical method you would have** with no missing data for each completed data set

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- Simple theoretically: merely a likelihood model for data (D_{obs}, M) and same parameters as when fully observed (μ, Σ)
- Complicated computationally: $D_{i,obs}$ has different elements observed for each i ; each observation is informative about different pieces of (μ, Σ)

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- **For social science survey data** (mostly ordinal scales): this is a reasonable choice for imputation, even if not for analysis

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- Equivalent to drawing from $\tilde{y}_i = X\tilde{\beta} + \tilde{\epsilon}_i$ (estimation, fundamental uncertainty)

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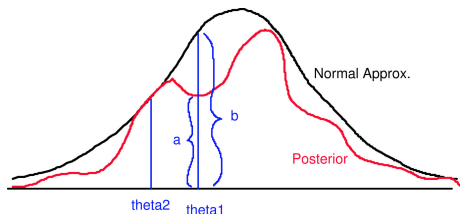
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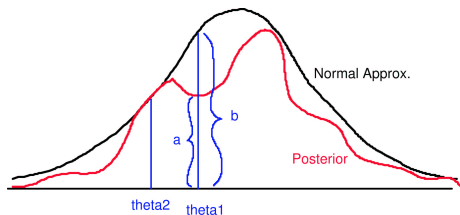
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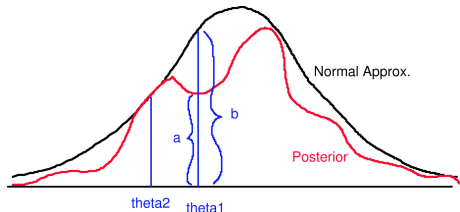


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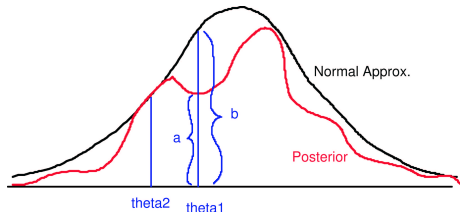
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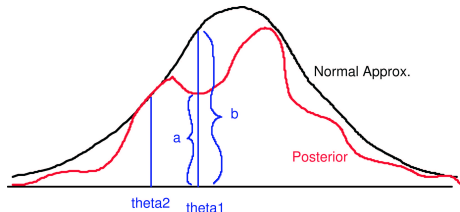
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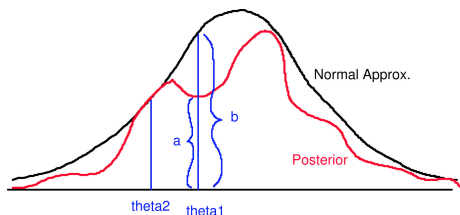
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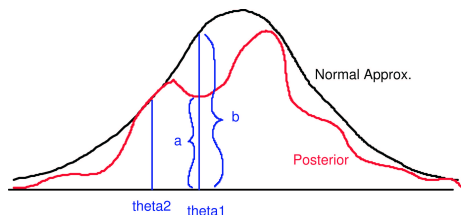
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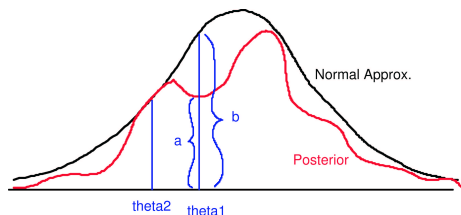
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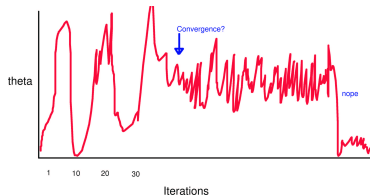
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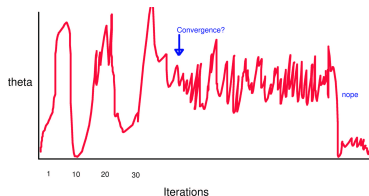
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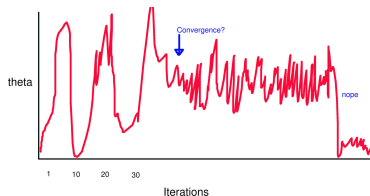
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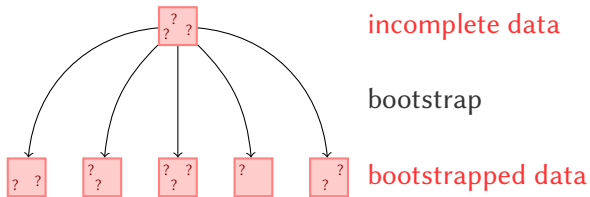
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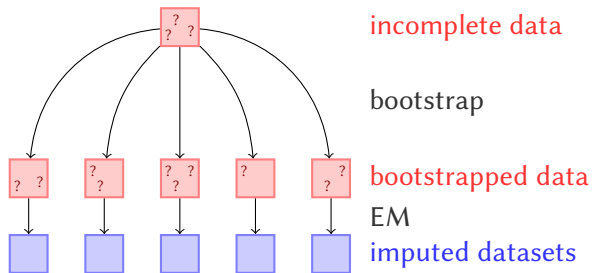


incomplete data

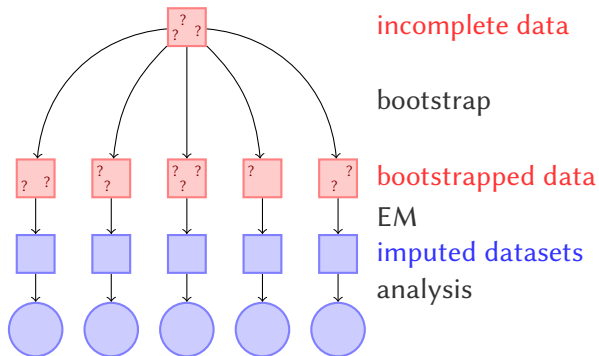
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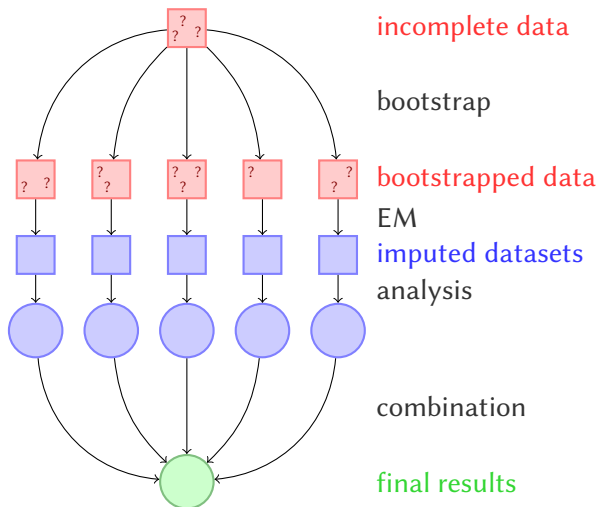
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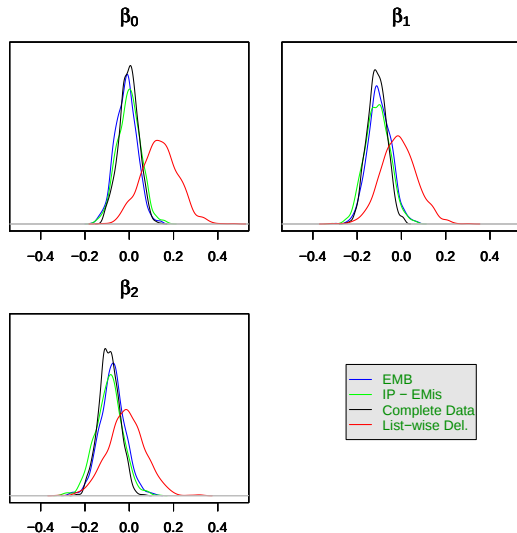
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Comparisons of Posterior Density Approximations



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Overview

Missingness Assumptions

Application Specific Methods

Multiple Imputation

Computational Algorithms

What Can Go Wrong

Time Series, Cross-Sectional Imputations

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I.e., you don't trust data to impute D_{mis} but trust it to analyze D_{obs}

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Overview

Missingness Assumptions

Application Specific Methods

Multiple Imputation

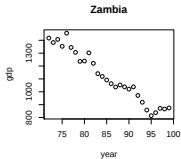
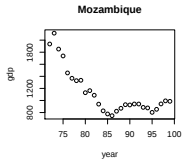
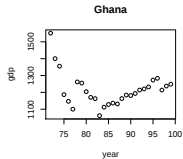
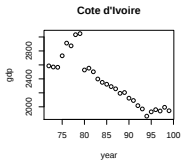
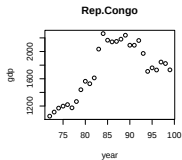
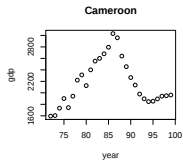
Computational Algorithms

What Can Go Wrong

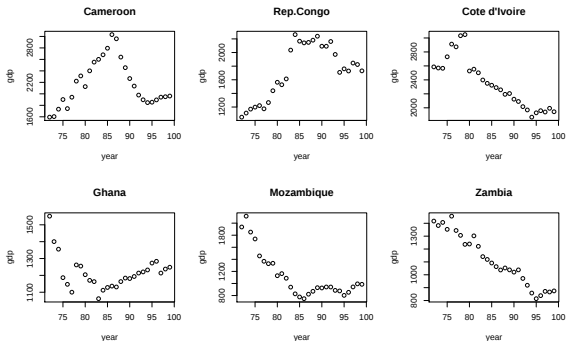
Time Series, Cross-Sectional Imputations

MI in Time Series Cross-Section Data

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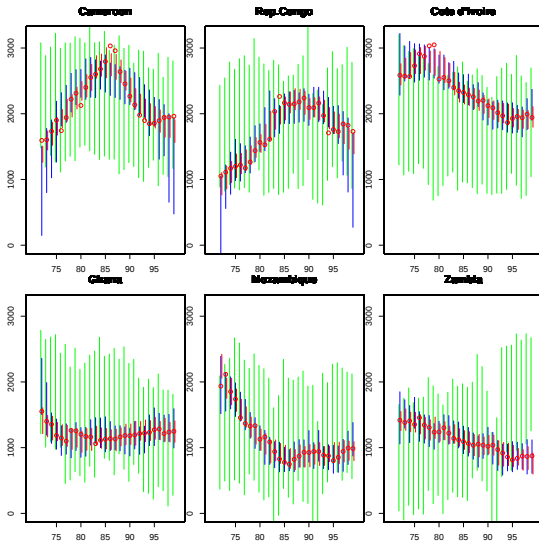


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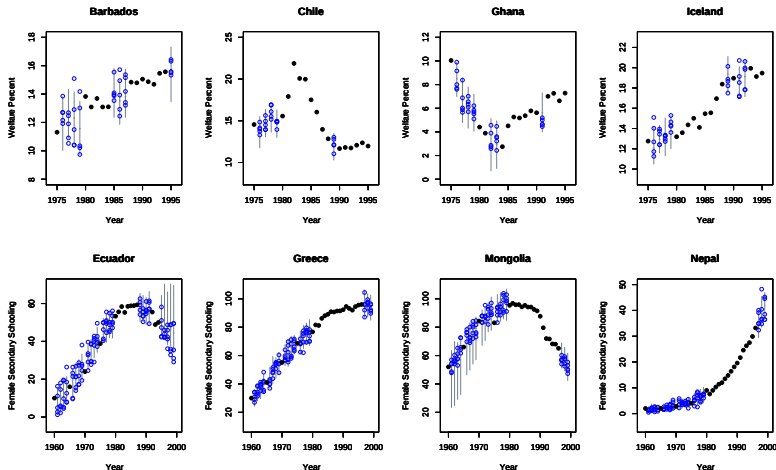
Include: (1) fixed effects, (2) time trends, and (3) priors for cells

Imputation one Observation at a time



Circles=true GDP; green=no time trends; blue=polynomials;
red=LOESS

Replication of Baum and Lake: Imputation Model Fit



Black = observed. Blue circles = five imputations; Bars = 95% CIs